AMENDMENTS TO THE SPECIFICATION:

Please amend the specification as follows:

Please replace paragraph 4, page 5, with the following.

Fig. 1A is a sectional view of a first fixed type constant velocity joint (see Figures 5 and 6) taking a maximum operating angle;

Please replace paragraph 6, page 5, with the following.

Fig. 2A is a sectional view of a second fixed type constant velocity joint (see Figure 7) taking a maximum operating angle;

Please replace paragraph 3, page 6, with the following.

Fig. 7 is a longitudinal sectional view of a second fixed type constant velocity joint;

Please replace paragraph 1, page 8, with the following.

In this embodiment, the center of curvature O1 of the guide grooves 14 of the outer joint member 10 and the center of curvature O2 of the guide grooves 24 of the inner joint member 20 are offset to opposite sides of the joint center O by an axially equal distance [[F]] f (in the example shown, the center O1 is on the opening side of the joint, and the center O2 is on the innermost side of the joint). In other words, the amount of offset [[F]] f of the center of curvature O1 of the guide grooves 14 is equal to the axial distance between the center of curvature O1 and the joint center O, and the amount of offset [[F]] f of the center of curvature O2 of the guide grooves 24 is equal to

2

the axial distance between the center of curvature O2 and the joint center O; thus the two are equal to each other. Therefore, the ball tracks defined by cooperation between the guide grooves 14 and 24 are wedge-shaped, with one axial end (in the illustrated embodiment, the opening side of the joint) opened.